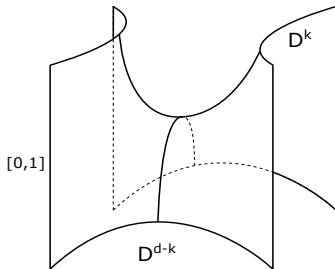
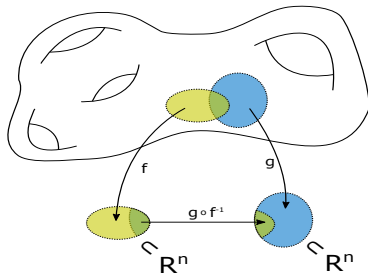


The action of $\text{Diff}(M)$ on $\mathcal{R}^+(M)$

Georg Frenck | November 27, 2019

INSTITUTE OF ALGEBRA AND GEOMETRY (IAG)



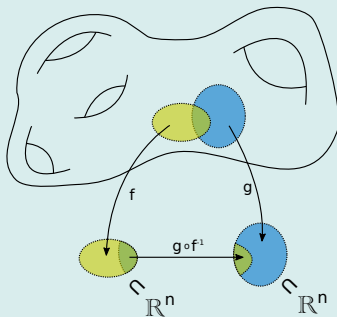
Introduction and Motivation

Definition

A **manifold** M is a second-countable Hausdorff space where every point $x \in M$ has a neighbourhood $x \in U_x$ which is homeomorphic to \mathbb{R}^n .

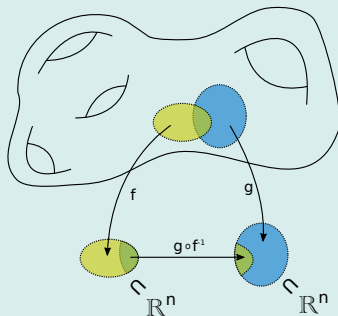
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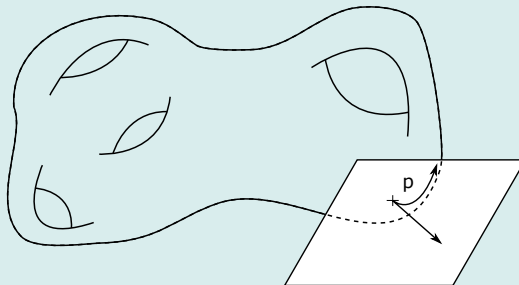
A manifold is called **smooth** if the transition functions are smooth.

Definition

Let M be a smooth manifold and $p \in M$. The **tangent space** $T_p M$ of M at p is defined as the “vector space of all directions on M emanating from p ”.

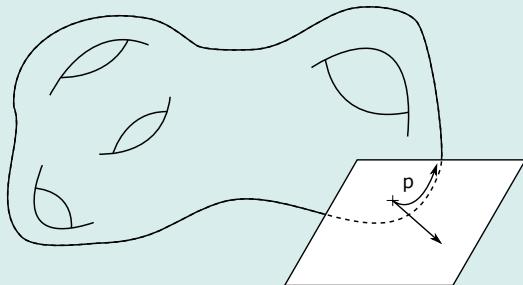
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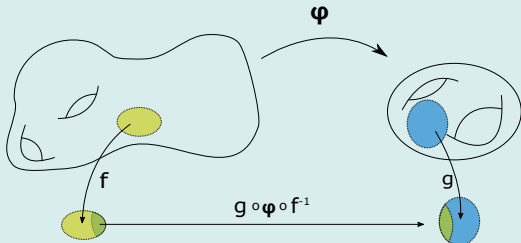
The collection of all tangent spaces is called the **tangent bundle** TM .

Definition

Let M, N be smooth manifolds. A **diffeomorphism** $\varphi: M \rightarrow N$ is a bijective, continuous and open map, such that φ and its inverse φ^{-1} are smooth through charts.

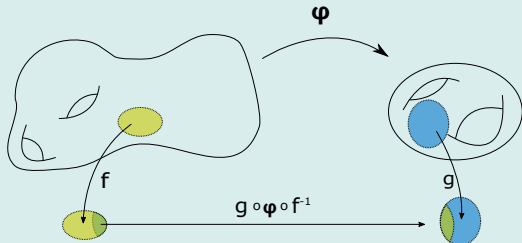
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We denote the **group of self-diffeomorphisms** of M by $\text{Diff}(M)$.

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A diffeomorphism $\varphi: (M, g) \rightarrow (M', g')$ of Riemannian manifolds is called **isometry** if $\varphi^* g' = g$.

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\rightsquigarrow Find isometry invariants of Riemannian metrics!

Scalar curvature

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Riemannian metric

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Riemannian metric \longrightarrow Measure length and angles

Scalar curvature

Riemannian metric \longrightarrow Measure length and angles \longrightarrow Measure volume

Scalar curvature

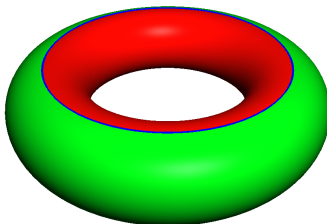
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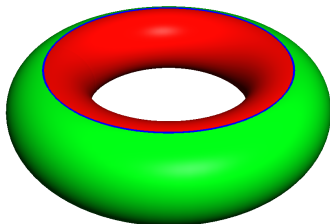
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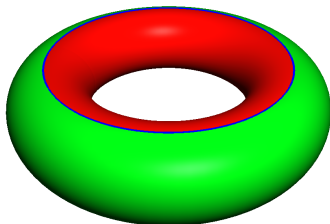


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(M, g) Riem. manifold \rightsquigarrow Scalar curvature: $\mathbf{scal}_g: M \longrightarrow \mathbb{R}$

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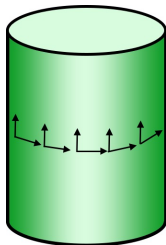
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Let M be a smooth manifold. An **orientation** on M is a compatible choice of orientations on each tangent space T_pM .

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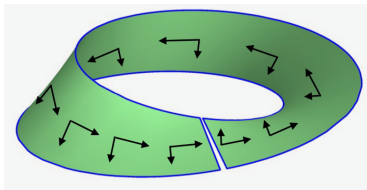
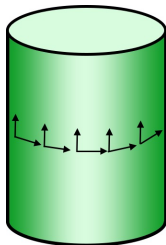
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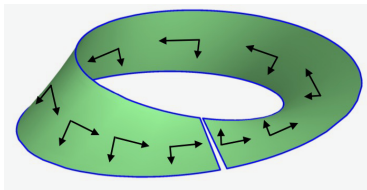
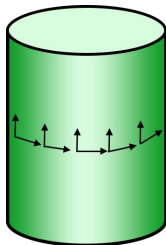
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Definition

Let M be an oriented manifold. A Spin-**structure** on M is a “higher orientation” of M .

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\rightsquigarrow Gromov–Lawson–Rosenberg conjecture

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- Show that this family gets mapped to a nontrivial element.

The space $\mathcal{R}^+(M)$

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Theorem (Hitchin 1974)

Let M be a Spin-manifold of dimension $(d - 1)$. Then there is a map $\pi_k(\mathcal{R}^+(M)) \rightarrow \text{KO}^{-d-k}(\text{pt})$, such that

$$\begin{aligned} \pi_0(\text{Diff}(S^{d-1})) &\rightarrow \pi_0(\mathcal{R}^+(S^{d-1})) \rightarrow \text{KO}^{-d}(\text{pt}) \\ [f] &\mapsto [f^* g_\circ] \end{aligned}$$

is surjective for $d \equiv 1, 2(8)$.

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Theorem (Hanke-Schick-Steimle, 2012)

If m is big enough, there exists a simply connected Spin -manifold M^{4m-1} such that

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Does this work for $M = S^{4m-1}$?

Theorem (F.)

Let $d \geq 7$, $d \neq 1, 2(8)$ and let M^{d-1} be as simply connected, stably parallelizable Spin-manifold. Let $f: M \rightarrow M$ be an orientation preserving diffeomorphism. Then $f^: \mathcal{R}^+(M) \rightarrow \mathcal{R}^+(M)$ is homotopic to the identity.*

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Remark

- 1 $f^* \sim \text{id} \Rightarrow \pi_0(f^*) = \text{id}: \pi_0(\mathcal{R}^+(M)) \rightarrow \pi_0(\mathcal{R}^+(M))$.
- 2 S^{d-1} is stably parallelizable.
 $\Rightarrow [f^*g_0] = [g_0]$ if $d \not\equiv 1, 2(8)$ and $d \geq 7$.
 \Rightarrow Hitchin's result cannot be extended to any other dimension.
- 3 If $d \equiv 1, 2(8) \Rightarrow [(f^2)^*g] = [g]$.

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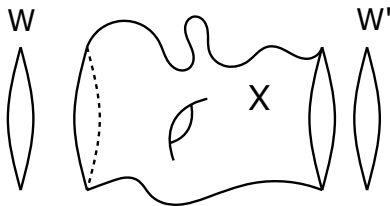
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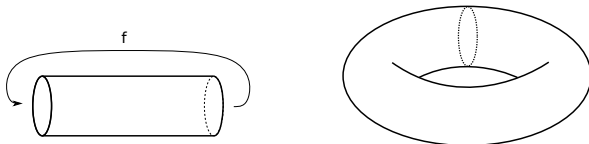
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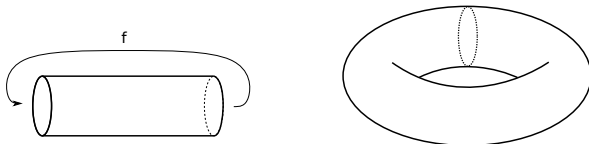
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Proposition (1973 Kreck)

If M satisfies the assumptions from before, then $[T_f] = 0 \in \Omega_d^{\text{Spin}}$ for every $f: M \xrightarrow{\cong} M$.

Construction of \mathcal{S}

Simplest piece: $\mathbf{tr} \varphi: M \rightsquigarrow M_\varphi$ for $\varphi: S^{k-1} \times D^{d-k} \hookrightarrow M$

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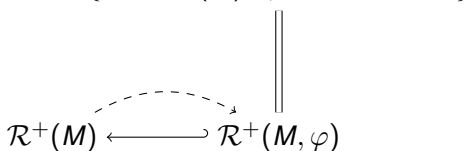


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There exists a V cobordant to $M \times [0, 1] \amalg W$ that admits a handle decomposition

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Question

Is (the homotopy class of) \mathcal{S}_W independent of these choices?

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If $d \geq 7$, the (homotopy class of the) map S_W is independent of the choice of handle decomposition of V .

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If $d \geq 7$, the (homotopy class of the) map S_W is independent of the choice of V cobordant to W .

Thank you for your attention!